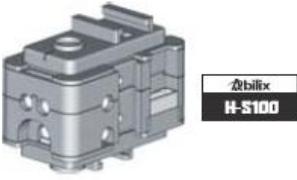
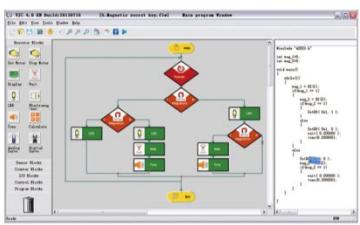




Physical and Technical Specification of H1-S

Detailed Properties:

A white product box for the Abilix Humanoid Robot H1-S. It features a grayscale image of the robot, the text "Humanoid Robot H1-S", and the Abilix logo.	This kit contains 18 executable module, 1 gyroscope, infrared distance recognition, wireless remote control sensors. Improved connection manual, supports the Humanoid construction. With advanced flow-chart programming C-language VJC, students can easily re-construct complicated projects like crab, humanoid, scorpion etc. Users can choose the sensors personally to get a deeper understanding on the intelligent robots.
1. Components Two small, metallic robotic components, likely sensors or actuators, shown side-by-side.	No screws construction parts, it includes controller, no less than 4 robotics steering motor (4 H-M24 motor), sensor (H-S100), power (charger/external power source), USB download line, user manner and VJC CD to support the robotics research. Support up to 28 teaching project.
2. Controller A rectangular electronic device with various ports, a small screen, and buttons. It is labeled "Abilix" and "ID 1".	The master chip of controller is ARM Cortex M3/32 bit, 6 H-M24 motor port, 4 pin duplexing I/O extension port, serial downloading cable, status light and interactive operation button, 1 standard extension 485 port. Integrated three-axis gyroscope module monitors the action and accelerated speed of robots, standard Bluetooth module (integrating of reception and transmission).
3. Motor A close-up view of a robotic motor assembly. It has two large black wheels attached to the bottom and a central metal housing. A small black label on the side reads "Abilix ID 1".	H-M24 motor, Maximum torque is 20kgf.cm, speed 70rpm, control accuracy is 0.29°. Robotics steering gear to connect multiple motors by series digital communications. It has multiple functions like temperature, location, speed, acceleration, torque and electricity etc., also the self-protection of overflowing and over-temperature, supports 360°limitless rotating, can be used as standard continuous current dynamo.

4. Remote Controller 	<p>The core chip of remote controller is ARM Cortex M3/32 bit with standard Bluetooth module working with AAA battery and manual operation system of power supply.</p>
5. Sensor 	<p>H-S100 highly integrated sensor module, 3 integrated ranging sensor module, 3 integrated light recognition sensor, 3 infrared distance signal transmission/reception along with buzzing (scale and time controllable), sound recognition.</p>
6. Software 	<p>Highly integrated graphic flow-chart programming, simplified C-language.</p>
7. Service	<p>Assembling guidelines, control code and construct course supported, basically are graphs with cable connection diagram.</p>

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